



**MASINDE MULIRO UNIVERSITY OF
SCIENCE AND TECHNOLOGY
(MMUST)**

MAIN CAMPUS

**UNIVERSITY EXAMINATIONS
2021/2022 SECOND SEMESTER EXAMINATIONS**

**FOR THE DEGREE
OF
BACHELOR OF SCIENCE IN ELECTRICAL AND COMMUNICATION
ENGINEERING**

COURSE CODE: ECE321

COURSE TITLE: CONTROL SYSTEMS I

DATE: TUESDAY, APRIL, 26TH, 2022

TIME: 12:00 – 2:00 PM

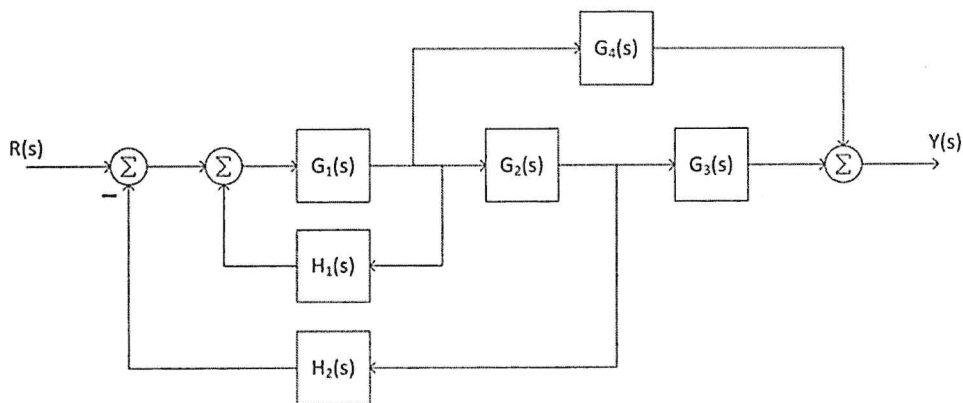
INSTRUCTIONS TO CANDIDATES

- *This Paper Consists of FIVE Questions.*
 - *Attempt Question ONE and TWO other Questions (Do not attempt more than expected).*
 - *Allow ONE hour for Question ONE and another ONE hour for TWO other Questions.*
 - *Question ONE carries 30 MARKS and all other Questions carry 20 MARKS each.*
 - *A BONUS will be awarded for clean and well-organized work.*
 - *Candidates are reminded to STRICTLY adhere to the Examination Rules and Regulations.*
 - **REQUIRED:** *Answer Booklet and Calculator.*
-

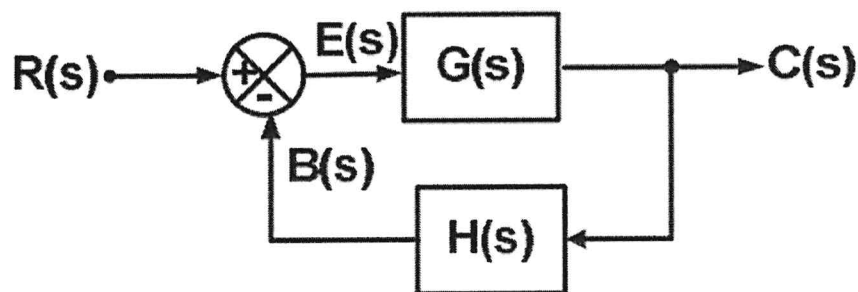
QUESTION ONE (COMPULSORY) (30 MARKS)

1. Explain the following terminologies as applied in control systems
 - i. Control system
 - ii. Controller
 - iii. System
 - iv. Feedback Signal

[4 Marks]
2. Discuss at least 3 classifications of control systems. **[6 Marks]**
3. Differentiate between the necessary condition and sufficient condition for stability in Routh-Hurwitz Stability Criterion. **[4 Marks]**
4. Differentiate between time response and frequency response in control systems. **[4 Marks]**
5. Simplify the block diagram using the block diagram reduction rules and determine the transfer function of the system. **[4 Marks]**



6. Consider a first-order system shown below, show that for unit step signal and unit ramp signal inputs, the unit response, $c(t)$ has both the transient and the steady-state terms and the unit response, $c(t)$ is an exponentially decaying signal for unit impulse input



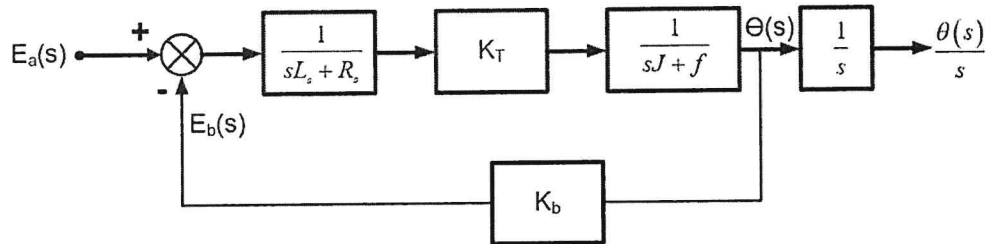
[6 Marks]

7. State if the following closed loop poles are stable or unstable
 - i. Closed-loop poles negative and real
 - ii. Closed-loop poles complex with negative real parts
 - iii. Closed-loop poles positive and real
 - iv. Closed-loop poles complex with positive real parts

[2 Marks]

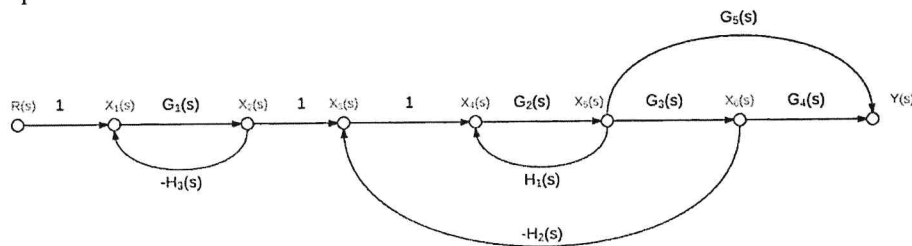
QUESTION TWO (20 MARKS)

1. Highlight at least 4 properties of signal flow graphs [4 Marks]
2. The block diagram below presents the armature type speed control of a DC motor, determine the transfer function and represent the block diagram in a signal flow graph.



[6 Marks]

3. Based on Mason's gain formula compute the transfer function from the signal flow graph below.



[4 Marks]

4. In a unity feedback control system, the open loop transfer function is given by

$$G(s) = \frac{k}{s(s+2)(s+4)}$$

Using Routh Hurwitz Criterion, determine the range of K for which the given system is stable. [6 Marks]

QUESTION THREE (20 MARKS)

1. Discuss at least 2 types of systems based on stability. [4 Marks]
2. Find the steady state error of an input signal $r(t) = \left(5 + 2t + \frac{t^2}{2}\right)u(t)$ of a unity negative feedback control system with.

$$G(s) = \frac{5(s+4)}{s^2(s+1)(s+20)}$$

[4 Marks]

3. Draw the root-locus of the feedback system whose open-loop transfer functions are given by.

$$G(s)H(s) = \frac{k}{s(s+2)(s+4)}$$

[8 Marks]

4. Discuss the effects of adding a pole or a zero to the root locus of a second-order system. [4 Marks]

QUESTION FOUR (20 MARKS)

- List at least two advantages and disadvantages of static error coefficient method? [4 Marks]
- Consider the system shown in Figure 1 below. To improve the performance of the system feedback is added to this system, which results in Figure 2. Determine the value of K so that the damping ratio of the new system is 0.4. Compare the overshoot, rise time, peak time and settling time and the nominal value of the systems shown in Figures 1 and 2.

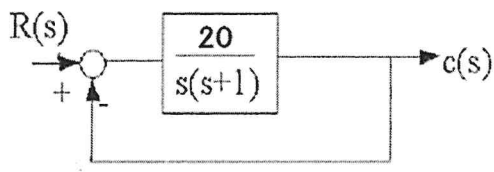


Figure 1

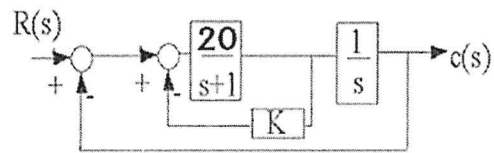


Figure 2

[8 Marks]

- Draw the Bode magnitude and phase plot of the open-loop transfer function $G(s)H(s)$ and determine gain margin, phase margin and absolute stability if

$$G(s)H(s) = \frac{1}{s(s+1)}$$

[8 Marks]

QUESTION FIVE (20 MARKS)

- Using appropriate equations and block diagram, discuss the effect of feedback on the following in control systems.
 - Overall Gain
 - Sensitivity
 - Stability
 - Noise[8 Marks]
- In a table format contrast between open loop and closed loop control systems. [4 Marks]
- Using Nyquist criterion, determine the stability of a feedback system whose open-loop transfer function is given by.

$$G(s)H(s) = \frac{55}{s(s+2)(s+4)}$$

[8 Marks]